MPI Derived Datatypes

Francesco Salvadore - f.salvadore@cineca.it

SuperComputing Applications and Innovation Department
Derived datatypes

What are?

MPI Derived datatypes are datatypes that are built from the basic MPI datatypes (e.g. MPI_INT, MPI_REAL, ...)

Why datatypes?

• Since all data is labeled by type, MPI implementations can support communication between processes on machines with very different memory representations and lengths of elementary datatypes (heterogeneous communication)

• Specifying application-oriented layout of data in memory
  - can reduce memory-to-memory copies in the implementation
  - allows the use of special hardware (scatter/gather) when available

• Specifying application-oriented layout of data on a file can reduce systems calls and physical disk I/O
Derived datatypes

You may need to send messages that contain

1. non-contiguous data of a single type (e.g. a sub-block of a matrix)
2. contiguous data of mixed types (e.g., an integer count, followed by a sequence of real numbers)
3. non-contiguous data of mixed types

Possible solutions:

1. make multiple MPI calls to send and receive each data element
   \[\rightarrow\] If advantageous, copy data to a buffer before sending it
2. use MPI_pack/MPI_Unpack to pack data and send packed data (datatype MPI_PACKED)
3. use MPI_BYTE to get around the datatype-matching rules. Like MPI_PACKED, MPI_BYTE can be used to match any byte of storage (on a byte-addressable machine), irrespective of the datatype of the variable that contains this byte.
   - Additional latency costs due to multiple calls
   - Additional latency costs due to memory copy
   - Not portable to a heterogeneous system using MPI_BYTE or MPI_PACKED
Packing data

- The user explicitly packs data into a contiguous buffer before sending it, and unpacks it from a contiguous buffer after receiving it.

- **MPI_Pack**(inbuf, incount, datatype, outbuf, outsize, position, comm)
  - pack: "incount" data of type "datatype" from buffer "inbuf"
  - to: contiguous storage area "outbuf" containing "outsize" bytes
  - "position" is the first location in the output buffer to be used for packing, updated when exiting from MPI_Pack
  - the communication "comm" to be used in the next has to be specified

- **MPI_Unpack**(inbuf, insize, position, outbuf, outcount, datatype, comm)
  - Unpacks a message into the receive buffer specified by "outbuf, outcount, datatype" from the buffer space specified by "inbuf and insize"

- **MPI_PACKED** is the datatype of packed data, to be send/received
Using MPI_Pack/Unpack

```c
int position; int n; float a, b; char buffer[100];
if (myrank == 0){
    n = 4; a = 1.; b = 2.; position = 0;
    // packing
    MPI_Pack(&a, 1, MPI_FLOAT, buffer, 100, &position, MPI_COMM_WORLD);
    MPI_Pack(&b, 1, MPI_FLOAT, buffer, 100, &position, MPI_COMM_WORLD);
    MPI_Pack(&n, 1, MPI_INT, buffer, 100, &position, MPI_COMM_WORLD);
    // communication
    MPI_Bcast(buffer, 100, MPI_PACKED, 0, MPI_COMM_WORLD);
} else {
    // communication
    MPI_Bcast(buffer, 100, MPI_PACKED, 0, MPI_COMM_WORLD);
    position = 0;
    // unpacking
    MPI_Unpack(buffer, 100, &position, &a, 1, MPI_FLOAT, MPI_COMM_WORLD);
    MPI_Unpack(buffer, 100, &position, &b, 1, MPI_FLOAT, MPI_COMM_WORLD);
    MPI_Unpack(buffer, 100, &position, &n, 1, MPI_INT, MPI_COMM_WORLD);
}
```
Why using Packed data

- Derived datatypes allow, in most cases, to avoid explicit packing and unpacking
  - the user specifies the layout of the data to be sent or received, and the communication library directly accesses a noncontiguous buffer.
- But packed data are provided for many reasons
  - **Compatibility**
    - with previous libraries
    - development of additional communication libraries layered on top of MPI
  - **Dynamic behaviour**
    - a message can be received in several parts, where the receive operation done on a later part may depend on the content of a former part
    - In MPI_Unpack, the count argument specifies the actual number of items that are unpacked (in MPI_Recv the count argument specifies the maximum number of items that can be received)
  - **Buffering**
    - outgoing messages may be explicitly buffered in user supplied space, thus overriding the system buffering policy
    - buffering is not the evil: explicit buffering may allow to implement efficient MPI patterns
Derived datatypes

You may need to send messages that contain

1. non-contiguous data of a single type (e.g. a sub-block of a matrix)
2. contiguous data of mixed types (e.g., an integer count, followed by a sequence of real numbers)
3. non-contiguous data of mixed types

Datatype solution:

1. The idea of MPI derived datatypes is to provide a simple, portable, elegant and efficient way of communicating non-contiguous or mixed types in a message.
   - During the communication, the datatype tells MPI system where to take the data when sending or where to put data when receiving.
2. The actual performances depend on the MPI implementation
3. Derived datatypes are also needed for getting the most out of MPI-I/O.
Definition

A general datatype is an opaque object able to describe a buffer layout in memory by specifying:

- A sequence of basic datatypes
- A sequence of integer (byte) displacements.

Typemap = \{(type 0, displ 0), \ldots, (type n-1, displ n-1)\}
- pairs of basic types and displacements (in byte)

Type signature = \{type 0, type 1, \ldots, type n-1\}
- list of types in the typemap
- gives size of each elements
- tells MPI how to interpret the bits it sends and received

Displacement:
- tells MPI where to get (when sending) or put (when receiving)
Typemap

Example:

Basic datatypes are particular cases of a general datatype, and are predefined:

\[ \text{MPI_INT} = \{(\text{int, 0})\} \]

General datatype with typemap

\[ \text{Typemap} = \{(\text{int, 0}), (\text{double, 8}), (\text{char, 16})\} \]
How to use

General datatypes are created and destroyed at run-time through calls to MPI library routines.

Implementation steps are:

1. Creation of the datatype from existing ones with a **datatype constructor**.
2. Allocation (**committing**) of the datatype before using it.
3. **Usage of the derived datatype** for MPI communications and/or for MPI-I/O
4. Deallocation (**freeing**) of the datatype after that it is no longer needed.
Construction of derived datatype

- **MPI_TYPE_CONTIGUOUS**
  - contiguous datatype
- **MPI_TYPE_VECTOR**
  - regularly spaced datatype
- **MPI_TYPE_CREATE_HVECTOR**
  - like vector, but the stride is specified in byte
- **MPI_TYPE_INDEXED**
  - variably spaced datatype
- **MPI_TYPE_CREATE_HINDEXED**
  - like indexed, but the stride is specified in byte
- **MPI_TYPE_CREATE_INDEXED_BLOCK**
  - particular case of the previous one
- **MPI_TYPE_CREATE_SUBARRAY**
  - subarray within a multidimensional array
- **MPI_TYPE_CREATE_DARRAY**
  - distribution of a ndim-array into a grid of ndim-logical processes
- **MPI_TYPE_CREATE_STRUCT**
  - fully general datatype
Committing and freeing

**MPI_TYPE_COMMIT (datatype)**

<table>
<thead>
<tr>
<th>INOUT datatype: datatype that is committed (handle)</th>
</tr>
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<tbody>
<tr>
<td>• Before it can be used in a communication or I/O call, each derived datatype has to be committed</td>
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**MPI_TYPE_FREE (datatype)**

<table>
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<th>INOUT datatype: datatype that is freed (handle)</th>
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<tr>
<td>• Mark a datatype for deallocation</td>
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<td>• Datatype will be deallocated when all pending operations are finished</td>
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MPI_TYPE_CONTIGUOUS

MPI_TYPE_CONTIGUOUS (count, oldtype, newtype)

IN count: replication count (non-negative integer)
IN oldtype: old datatype (handle)
OUT newtype: new datatype (handle)

- **MPI_TYPE_CONTIGUOUS** constructs a typemap consisting of the **replication** of a **datatype** into contiguous locations.
- newtype is the datatype obtained by concatenating count copies of oldtype.
count = 4;
MPI_Type_contiguous(count, MPI_FLOAT, &rowtype);

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<th>1.0</th>
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MPI_Send(&a[2][0], 1, rowtype, dest, tag, comm);

1 element of rowtype
MPI_TYPE_VECTOR

Consist of a number of elements of the same datatype repeated with a certain stride

oldtype

newtype

blocklength = 3 elements

stride = 5 el.s between block starts

count = 2 blocks
Example

count = 4; blocklength = 1; stride = 4;
MPI_Type_vector(count, blocklength, stride, MPI_FLOAT, &columntype);

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a[4][4]

MPI_Send(&a[0][1], 1, columntype, dest, tag, comm);

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</table>

1 element of columntype
MPI_TYPE_CREATE_HVECTOR

MPI_TYPE_CREATE_HVECTOR (count, blocklength, stride, oldtype, newtype)

IN count: Number of blocks (non-negative integer)
IN blocklen: Number of elements in each block (non-negative integer)
IN stride: Number of bytes between start of each block (integer)
IN oldtype: Old datatype (handle)
OUT newtype: New datatype (handle)

• It’s identical to MPI_TYPE_VECTOR, except that stride is given in bytes, rather than in elements
• “H” stands for heterogeneous
MPI_TYPE_INDEXED

MPI_TYPE_INDEXED (count, array_of_blocklengths, array_of_displacements, oldtype, newtype)

IN count: number of blocks – also number of entries in
array_of_blocklengths and array_of_displacements
(non-negative integer)
IN array_of_blocklengths: number of elements per block
(array of non-negative integers)
IN array_of_displacements: displacement for each block, in multiples of oldtype extent
(array of integer)
IN oldtype: old datatype (handle)
OUT newtype: new datatype (handle)

• Creates a new type from blocks comprising identical elements
• The size and displacements of the blocks can vary

oldtype

newtype

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count=3, array_of_blocklengths=(/2,3,1/), array_of_displacements=(/0,3,8/)
Example 1

\[
\begin{align*}
\text{count} &= 2; \\
\text{blocklengths}[0] &= 4; & \text{blocklengths}[1] &= 2; \\
\text{displacements}[0] &= 5; & \text{displacements}[1] &= 12;
\end{align*}
\]

\[
\begin{array}{cccccccccccccccc}
1.0 & 2.0 & 3.0 & 4.0 & 5.0 & 6.0 & 7.0 & 8.0 & 9.0 & 10.0 & 11.0 & 12.0 & 13.0 & 14.0 & 15.0 & 16.0 \\
\end{array}
\]

a[16]

\[
\text{MPI\_Type\_indexed(count, blocklengths, displacements, MPI\_FLOAT, \&indextype);} \\
\text{MPI\_Send(\&a, 1, indextype, dest, tag, comm);}
\]
Example 2

/* upper triangular matrix */
double a[100][100];
int displ[100], blocklen[100], int i;
MPI_Datatype upper;
/* compute start and size of the rows */
for (i=0; i<100; i++){
    displ[i] = 100*i+i;
    blocklen[i] = 100-i;
}
/* create and commit a datatype for upper triangular matrix */
MPI_Type_indexed (100, blocklen, disp, MPI_DOUBLE, &upper);
MPI_Type_commit (&upper);
/* ... send it ...*/
MPI_Send (a, 1, upper, dest, tag, MPI_COMM_WORLD);
MPI_Type_free (&upper);
MPI_TYPE_CREATE_HINDEXED

MPI_TYPE_CREATE_HINDEXED (count, array_of_blocklengths, array_of_displacements, oldtype, newtype)

IN count: number of blocks – also number of entries in array_of_blocklengths and array_of_displacements (non-negative integer)
IN array_of_blocklengths: number of elements in each block (array of non-negative integers)
IN array_of_displacements: byte displacement of each block (array of integer)
IN oldtype: old datatype (handle)
OUT newtype: new datatype (handle)

- This function is identical to MPI_TYPE_INDEXED, except that block displacements in array_of_displacements are specified in bytes, rather than in multiples of the oldtype extent
Similar to MPI_TYPE_INDEXED, except that the block-length is the same for all blocks.

There are many codes using indirect addressing arising from unstructured grids where the blocksize is always 1 (gather/scatter). This function allows for constant blocksize and arbitrary displacements.
The subarray type constructor creates an MPI datatype describing an n-dimensional subarray of an n-dimensional array. The subarray may be situated anywhere within the full array, and may be of any nonzero size up to the size of the larger array as long as it is confined within this array.
Example

MPI_TYPE_CREATE_SUBARRAY (ndims, array_of_sizes, array_of_subsizes, array_of_starts, order, oldtype, newtype)

double subarray[100][25];
MPI_Datatype filetype;
int sizes[2], subsizes[2], starts[2];
int rank;

MPI_Comm_rank(MPI_COMM_WORLD, &rank);

sizes[0]=100; sizes[1]=100;
subsizes[0]=100; subsizes[1]=25;
starts[0]=0; starts[1]=rank*subsizes[1];

MPI_Type_create_subarray(2, sizes, subsizes, starts, MPI_ORDER_C, MPI_DOUBLE, &filetype);

MPI_Type_commit(&filetype);
MPI_TYPE_CREATE_DARRAY (size, rank, ndims, array_of_gsizes, array_of_distribs, array_of_dargs, array_of_psizes, order, oldtype, newtype)

IN size: size of process group (positive integer)
IN rank: rank in process group (non-negative integer)
IN ndims: number of array dimensions as well as process grid dimensions (positive integer)
IN array_of_gsizes: number of elements of type oldtype in each dimension of global array (array of positive integers)
IN array_of_distribs: distribution of array in each dimension (array of state, 
  MPI_DISTRIBUTE_BLOCK - Block distribution, MPI_DISTRIBUTE_CYCLIC – Cyclic distribution, MPI_DISTRIBUTE_NONE - Dimension not distributed. )
IN array_of_dargs: distribution argument in each dimension (array of positive integers, 
  MPI_DISTRIBUTE_DFLT_DARG specifies a default distribution argument)
IN array_of_psizes: size of process grid in each dimension (array of positive integers)
IN order: array storage order flag (state, i.e. MPI_ORDER_C or MPI_ORDER_FORTRAN)
IN oldtype: old datatype (handle)
OUT newtype: new datatype (handle)
MPI_TYPE_CREATE_DARRAY

- Distribution scheme: (CYCLIC(2), BLOCK)
- Cyclic distribution in first dimension with strips of length 2
- Block distribution in second dimension
- Distribution of global garray onto the larray in each of the 2x3 processes
- Garray on the file:
  - E.g., larray on process (0,1):
**MPI_TYPE_CREATE_DARRAY**

```c
int MPI_Type_create_darray (int size, int rank, int ndims, int array_of_gsizes[], int array_of_distribs[],
int array_of_dargs[], int array_of_psizes[], int order, MPI_Datatype oldtype, MPI_Datatype *newtype)
```

```plaintext
array_of_gsize[2] = (/20,30/)
array_of_distribs[2] = (/MPI_DISTRIBUTE_CICLIC, MPI_DISTRIBUTE_BLOCK/)
array_of_dargs[2] = (/2, MPI_DISTRIBUTE_DFLT_DARG/)
array_of_psize[2] = (/2,3/)```
**MPI_TYPE_CREATE_DARRAY**

- Creates a data type corresponding to a distributed, multidimensional array
- N-dimensional distributed/strided sub-array of an N-dimensional array
- Fortran and C order allowed
- Fortran and C calls expect indices starting from 0
- An example is provided in the MPI2-I/O presentation.

```c
int MPI_Type_create_darray (int size, int rank, int ndims,
                             int array_of_gsizes[], int array_of_distribs[],
                             int array_of_dargs[], int array_of_psizes[], int order,
                             MPI_Datatype oldtype, MPI_Datatype *newtype)
```
Size and Extent

The MPI datatype for structures - MPI_TYPE_CREATE_STRUCT - requires dealing with memory addresses and further concepts:

**Typemap:** pairs of basic types and displacements

**Extent:** The extent of a datatype is the span from the lower to the upper bound *(including “holes”)*

**Size:** The size of a datatype is the net number of bytes to be transferred *(without “holes”)*

![Diagram showing the relationship between int, char, double, and a derived datatype]
Size vs. extent of a datatype

Basic datatypes:
- size = extent = number of bytes used by the compiler

Derived datatypes:
- extent include holes but...
- beware of the type vector: final holes are a figment of our imagination

• size = 6 x size of “old type”
• extent = 10 x extent of “old type”
Query size and extent of datatype

- Returns the total number of bytes of the entry datatype

\[
\text{MPI\_TYPE\_SIZE (datatype, size)}
\]

IN datatype: datatype (handle)
OUT size: datatype size (integer)

- Returns the lower bound and the extent of the entry datatype

\[
\text{MPI\_TYPE\_GET\_EXTENT (datatype, lb, extent)}
\]

IN datatype: datatype to get information on (handle)
OUT lb: lower bound of datatype (integer)
OUT extent: extent of datatype (integer)
Extent

• Extent controls how a datatype is used with the count field in a send and similar MPI operations

• Consider

```fortran
call MPI_Send(buf,count,datatype,...)
```

• What actually gets sent?

```fortran
do i=0,count-1
   call MPI_Send(bufb(1+i*extent(datatype)),1,datatype,...)
endo
```

where `bufb` is a byte type like `integer*1`

• `extent` is used to decide where to send from (or where to receive to in `MPI_Recv`) for `count>1`
  - Normally, this is right after the last byte used for `(i-1)`
This subroutine returns a new datatype that represents count blocks. Each block is defined by an entry in array_of_blocklengths, array_of_displacements and array_of_types.

Displacements are expressed in bytes (since the type can change!)

To gather a mix of different datatypes scattered at many locations in space into one datatype that can be used for the communication.
Using extents (not safe)

```
struct {
  float x, y, z, velocity;
  int n, type;
} Particle;

Particle particles[NELEM];
```

```
MPI_Type_extent(MPI_FLOAT, &extent);

count = 2;
bloc...
struct {
    float x, y, z, velocity;
    int n, type;
} Particle;

Particle particles[NELEM];

int count, blockcounts[2];
MPI_Aint displ[2];
MPI_Datatype particletype, oldtypes[2];

count = 2;
blockcounts[0] = 4; blockcount[1] = 2;
oldtypes[0] = MPI_FLOAT; oldtypes[1] = MPI_INT;

MPI_Type_extent(MPI_FLOAT, &extent);
disp[0] = 0; disp[1] = 4*extent;

MPI_Type_create_struct (count, blockcounts, displ, oldtypes, &particletype);

MPI_Type_commit(&particletype);

MPI_Send (particles, NELEM, particletype, dest, tag, MPI_COMM_WORLD);

MPI_Free(&particletype);
Mind the alignments!

- C struct may be automatically padded by the compiler, e.g.

```c
struct mystruct {
    char a;
    int b;
    char c;
} x
```

- Using extents to handle structs is not safe! Get the addresses

```c
struct mystruct {
    char a;
    char gap_0[3];
    int b;
    char c;
    char gap_1[3];
} x
```

- The address of the variable is returned, which can then be used to determine the correct relative displacements
- Using this function helps wrt portability

```
MPI_GET_ADDRESS (location, address)
IN location: location in caller memory (choice)
OUT address: address of location (integer)
```
Using displacements

struct PartStruct {
    char class;
    double d[6];
    int b[7];
} particle[100];

- handles inner padding...
- but not trailing padding (important when sending more than one struct)

MPI_Datatype ParticleType;
int count = 3;
MPI_Datatype type[3] = {MPI_CHAR, MPI_DOUBLE, MPI_INT};
int blocklen[3] = {1, 6, 7};
MPI_Aint disp[3];

MPI_Get_address(&particle[0].class, &disp[0]);
MPI_Get_address(&particle[0].d, &disp[1]);
MPI_Get_address(&particle[0].b, &disp[2]);
/* Make displacements relative */
disp[2] -= disp[0]; disp[1] -= disp[0]; disp[0] = 0;

MPI_Type_create_struct (count, blocklen, disp, type, &ParticleType);
MPI_Type_commit (&ParticleType);

MPI_Send(particle,100,ParticleType,dest,tag,comm);
MPI_Type_free (&ParticleType);
Resizing datatypes

- Using addresses, is still unsafe for arrays of struct because of possible alignments of the last member of the structure.

**MPI_TYPE_CREATE_RESIZED** (oldtype, newlb, newextent, newtype)

- **IN oldtype**: input datatype (handle)
- **IN newlb**: new lower bound of datatype (integer, in terms of bytes)
- **IN newextent**: new extent of datatype (integer, in term of bytes)
- **OUT newtype**: output datatype (handle)

- Returns in newtype a handle to a new datatype that is identical to oldtype, except that the lower bound of this new datatype is set to be “lb”, and its upper bound is set to be “lb + extent”.
- Modifying extent is useful to handle alignments of the last items of structs.
  - Crucial when communicating more than one derived data-type.
- Modifying also the lower bound can be confusing, use with particular care.
Example

/* Sending an array of structs portably */
struct PartStruct particle[100];
MPI_Datatype ParticleType;
...

/* check that the extent is correct */
MPI_Type_get_extent(ParticleType, &lb, &extent);
If ( extent != sizeof(particle[0]) ) {
    MPI_Datatype old = ParticleType;
    MPI_Type_create_resized ( old, 0, sizeof(particle[0]), &ParticleType);
    MPI_Type_free(&old);
}
MPI_Type_commit ( &ParticleType);
Fortran types

- According to the standard the memory layout of Fortran derived data is much more liberal.
- An array of types may be implemented as 5 arrays of scalars!

```fortran
! Fortran types

• The memory layout is guaranteed using sequence or bind(C) type attributes
  – Or by using the (old style) commons...
• With Fortran 2003, MPI_Type_create_struct may be applied to common blocks, sequence and bind(C) derived types
  – it is implementation dependent how the MPI implementation computes the alignments (sequence, bind(C) or other)
• The possibility of passing particles as a type depends on MPI implementation: try particle%x and/or study the MPI standard and Fortran 2008 constructs
```

```fortran
! Fortran types

type particle
  real :: x, y, z, velocity
  integer :: n
end type particle

type(particle) :: particles(Np)
```

```fortran
! Fortran types

```

```fortran
! Fortran types

type particle
  real :: x, y, z, velocity
  integer :: n
end type particle

type(particle) :: particles(Np)
```
call MPI_GET_ADDRESS(foo%i, disp(1), ierr)
call MPI_GET_ADDRESS(foo%x, disp(2), ierr)
call MPI_GET_ADDRESS(foo%d, disp(3), ierr)
call MPI_GET_ADDRESS(foo%l, disp(4), ierr)
base = disp(1)
disp(1) = disp(1) – base ; disp(2) = disp(2) - base
disp(3) = disp(3) – base ; disp(4) = disp(4) - base
blocklen(1) = 1 ; blocklen(2) = 1
blocklen(3) = 1 ; blocklen(4) = 1
type(1) = MPI_INTEGER ; type(2) = MPI_REAL
type(3) = MPI_DOUBLE_PRECISION ; type(4) = MPI_LOGICAL
call MPI_TYPE_CREATE_STRUCT(4, blocklen, disp, type, newtype, ierr)
call MPI_TYPE_COMMIT(newtype, ierr)
call MPI_SEND(foo%i, 1, newtype, dest, tag, comm, ierr)
   ! or
call MPI_SEND(foo, 1, newtype, dest, tag, comm, ierr)
   ! expects that base == address(foo%i) == address(foo)
call MPI_GET_ADDRESS(fooarr(1), disp(1), ierr)
call MPI_GET_ADDRESS(fooarr(2), disp(2), ierr)
extent = disp(2) - disp(1) ; lb = 0
call MPI_TYPE_CREATE_RESIZED(newtype, lb, extent, newarrtype, ierr)
call MPI_TYPE_COMMIT(newarrtype, ierr)
call MPI_SEND(fooarr, 5, newarrtype, dest, tag, comm, ierr)
Performances

- Performance depends on the datatype - more general datatypes are often slower
  - some MPI implementations can handle important special cases: e.g., constant stride, contiguous structures
- Overhead is potentially reduced by:
  - Sending one long message instead of many small messages
  - Avoiding the need to pack data in temporary buffers
- Some implementations are slow
Hands-on: using PLX

- Connect to PLX front-end:
  ```
  # ssh <user_name>@login.plx.cineca.it
  # module load profile/advanced
  ```
- Load the modules to use compiler and MPI, e.g. using Intel
  ```
  # module av openmpi
  # module load intel/cs-xe-2013--binary
  # module load openmpi/1.6.3--intel--cs-xe-2013--binary
  ```
- If you need to use computing nodes (you do not need for these hands-ons), you have to write a script to be submitted
  ```
  #!/bin/bash
  #PBS -l walltime=00:10:00 # or other needed time
  #PBS -l select=1:ncpus=1  # or ncpus=N, N is the number of CORES
  #PBS -q private
  cd $PBS_O_WORKDIR
  # (a) Load Modules, e.g.
  module load profile/advanced
  module load intel/cs-xe-2013--binary openmpi/1.6.3--intel--cs-xe-2013--binary
  # (b) Run executables
  ./matmul >& matmul.out
  ```
- Submit using
  ```
  # qsub <script_name>
  ```
Hands-on: vectors and extents

Write a program working only with 2 MPI processes

- for each process, define a matrix $A$ (nx$n$)
- rank=0 fills $A$ with 0, while rank=1 fills with 1
- define a datatype to handle a column (C) or a row (Fortran) of $A$
- extract size and extent of this type: is what you expect?
- rank=0 sends to rank=1 the first column/row overwriting the $A$ column/row
- check the results printing the matrix on screen
- modify the code to send the first nb columns/rows of $A$: do you have to change the type? can you send two items of the new type?

\[
\begin{array}{cccccc}
0 & 0 & 1 & 1 & 1 & 1 \\
0 & 0 & 1 & 1 & 1 & 1 \\
0 & 0 & 1 & 1 & 1 & 1 \\
0 & 0 & 1 & 1 & 1 & 1 \\
0 & 0 & 1 & 1 & 1 & 1 \\
\end{array}
\]

Final $A$ for rank=1

n=5 ; nb=2

\[
\begin{array}{cccccc}
0 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 0 \\
1 & 1 & 1 & 1 & 1 & 1 \\
1 & 1 & 1 & 1 & 1 & 1 \\
1 & 1 & 1 & 1 & 1 & 1 \\
\end{array}
\]

C

Fortran

<ggd>
QUESTIONS ???